

**AMENDMENTS TO THE CLAIMS**

Claims 1-5 (Canceled).

6. (Currently Amended) A method of searching for an object in still or video images by processing signals corresponding to the images, the method comprising:

~~deriving a view descriptor of the first outline of a three-dimensional object,~~

~~deriving at least one additional view descriptor of the outline of the object in a different view,~~

~~associating the two or more view descriptors to form at least one stored object descriptor containing the view descriptors,~~

~~inputting a query to the computer in the form of at least two-dimensional outline of the object,~~

providing a plurality of stored image representations of three-dimensional objects, each image representation being associated with an object descriptor;

each object descriptor including a plurality of view descriptors, each view descriptor a representation of one of the three-dimensional objects from a different perspective view of the three-dimensional object;

inputting a query ~~to the computer~~ in the form of at least a two-dimensional outline of ~~the~~ an object;

deriving a query object descriptor of the query object;  
comparing said query object descriptor with at least one of  
said object descriptors; ~~and~~  
selecting and displaying at least one result corresponding to  
an one of the image representations containing an object for which  
the comparison between the ~~respective~~ associated object descriptor  
and the query object descriptor indicates a degree of similarity  
between the query object and said object.

7. (Previously Presented) A method as claimed in claim 6  
wherein a query is input in the form of two or more two-dimensional  
outlines of an object, and wherein a query view descriptor is  
derived for each said outline, and wherein the step of comparing  
comprises comparing each said query view descriptor with each view  
descriptor in each stored object descriptor to derive a plurality  
of view-similarity values.

8. (Previously Presented) A method as claimed in claim 7  
wherein the view-similarity values are analyzed to derive object  
similarity values.

9. (Previously Presented) A method as claimed in claim 6,  
wherein at least some of the object descriptors include view-

independent descriptors which are related to shape and/or size of the object, and wherein the method comprises inputting a view-independent query value and the step of comparing compares the query value with the view-independent descriptors for the stored object descriptors.

10. (Currently Amended) A method as claimed in claim 6, wherein the query descriptor is derived using a curvature scale space representation of ~~the~~ a query object outline.

Claims 11-32 (canceled).

33. (Currently Amended) A method of searching for an object in still or video images by processing signals corresponding to the images, the method comprising:

receiving a query descriptor representing a two-dimensional view of ~~an~~ a query object;

comparing the query descriptor with a plurality of stored object descriptors each representing ~~an identical~~ a three-dimensional object ~~in a different view~~, each object descriptor including a plurality of view descriptors, each view descriptor a representation of the object from a different perspective view of the three-dimensional object, each stored object descriptor being

associated with an image representation of the object; and

selecting the three-dimensional object and associated image representation when ~~one~~ of the respective stored object descriptors matches the query descriptor.

34. (Previously Presented) The method of searching according to claim 33, wherein the query descriptor is derived using a curvature scale space representation of an outline of the query object.

35. (Previously Presented) The method of searching according to claim 34, wherein the stored descriptor is derived using a curvature scale space representation of an outline of the three-dimensional object.

36. (New) The method of claim 6, further comprising:  
deriving an object descriptor for an object in an image by:  
deriving a view descriptor of a first outline of a three-dimensional object in the image,

deriving at least one additional view descriptor of the outline of the object in a different perspective view from the perspective view in the image, and

associating the two or more view descriptors to form the

object descriptor.

37. (New) The method of claim 6, wherein said selecting and displaying includes selecting and displaying an image representation of an object having a different perspective view from perspective view of said query object based on said query object matching with at least two view descriptors including a view descriptor not representing perspective view of the object in the image representation.

38. (New) The method of claim 33 wherein one of the view descriptors corresponds to a view of the object as the object appears in the respective image representation.

39. (New) The method of claim 33 wherein one of the view descriptors corresponds to a perspective view of the object different from the perspective view of the object as the object appears in the respective image.

40. (New) The method of claim 33, wherein said selecting includes selecting and displaying an image representation including an object having a different perspective view from perspective view of said query object based on said query object matching with at

least two view descriptors including a view descriptor not representing view of the object in the image.

41. (New) The method of claim 6, wherein each said view descriptor is a different representation of the object from a different perspective view of the three-dimensional object.